



2-quadrant blade spindle torque

References

- J. Dang, J. Brouwer, R. Bosman and C. Pouw (2012) 'Quasi-Steady Two-Quadrant Open Water Tests for the Wageningen Propeller C- and D-Series', proceedings of the 29th ONR, Gothenburg, Sweden, 26-31 August.
- J. Dang, H. van der Boom and J.Th. Ligtelijn (2013), "The Wageningen C- and D-Series Propellers", Proceedings of FAST'13, Amsterdam, December.

Research institute MARIN is a provider of advanced expertise and independent research to the maritime industry. Using the newest test facilities and simulators and working together with an extensive innovation and research network, we achieve our goal: the development of cleaner, safer and smarter ships and a sustainable use of the sea.

For more information contact the MARIN Software Group
 T +31 317 49 32 37
 E mmsg@marin.nl

The data sets contain the propeller thrust and torque coefficients as conventional propeller series, as well as the propeller blade spindle torque coefficients, at all pitch settings and for the complete two-quadrant operations.

Propeller geometry

The propeller geometry of all series is parameterised, fitted and smoothed into polynomials, before the series propeller models were manufactured and tested. The propeller geometry is included in the software.

Software

The software has three functions:

- **Selection and/or design of a propeller from the series:** In this function, the software searches the optimal propeller diameter or propeller shaft rotation rate at given ship operation condition, which can be sailing ahead or bollard pulling ahead, in order to balance the available power or needed thrust. Constraints such as the criteria on cavitation performance are taken into account.
- **Generate propeller geometry:** When a propeller is selected or designed, the software will generate the propeller geometry according to the geometry polynomials.
- **Hydrodynamic analysis and scenario studies:** With the selected or designed propeller, the software can predict hydrodynamic performance, such as the ship speed power relations, the bollard ability, the crash stop, the astern operations, the combinatory curves, and any predefined operation scenario studies.

The MCD software contains a computation core (written in C# and compiled into a .DLL) and a graphic interface based on Quaestor environment for the MS Windows® system. The computation core contains all hydrodynamic data sets and takes care of the interpolation and extrapolation of the hydrodynamic data to any geometric and operational conditions.

The graphic interface takes care of input and output, the ship operation conditions, the engine and the mechanical drives. It also balances power or thrust during the selection of the propeller and optimises the propeller diameter or shaft rotation rate. Hydrodynamic analysis like scenario studies for speed power, for bollard pull, for combinatory curves, etc. have all been taken care of by the interface.

Furthermore, the interface presents the input for the software tools orderly and well structured. All input and (intermediate) output is managed in folders, each being part of a project. Data consistency is maintained by Quaestor, so if you make any change in one of the inputs, the framework will re-execute all dependent calculations.

The software is a must-have for designers, shipyards, operators and classes.

Definition of T , Q and Q_{blade}

